## $x=1$

## let $x=1$ in ...

## $x(1)$.

## ! $x(1)$

## Programming Language Theory

## Denotational Semantics

Ralf Lämmel

## Recall: Big-step operational semantics of While language

$$
\begin{array}{ll}
{\left[\mathrm{ass}_{\mathrm{ns}}\right]} & \langle x:=a, s\rangle \rightarrow s[x \mapsto \mathcal{A} \llbracket a \rrbracket s] \\
{\left[\mathrm{skip}_{\mathrm{ns}}\right]} & \langle\text { skip }, s\rangle \rightarrow s \\
{\left[\mathrm{comp}_{\mathrm{ns}}\right]} & \frac{\left\langle S_{1}, s\right\rangle \rightarrow s^{\prime},\left\langle S_{2}, s^{\prime}\right\rangle \rightarrow s^{\prime \prime}}{\left\langle S_{1} ; S_{2}, s\right\rangle \rightarrow s^{\prime \prime}} \\
{\left[\mathrm{if}_{\mathrm{ns}}^{\mathrm{tt}]}\right.} & \frac{\left\langle S_{1}, s\right\rangle \rightarrow s^{\prime}}{\left\langle\text { if } b \text { then } S_{1} \text { else } S_{2}, s\right\rangle \rightarrow s^{\prime}} \text { if } \mathcal{B} \llbracket b \rrbracket s=\mathbf{t t} \\
{\left[\mathrm{ifins}_{\mathrm{ff}]}\right.} & \frac{\left\langle S_{2}, s\right\rangle \rightarrow s^{\prime}}{\left\langle\text { if } b \text { then } S_{1} \text { else } S_{2}, s\right\rangle \rightarrow s^{\prime}} \text { if } \mathcal{B} \llbracket b \rrbracket s=\mathbf{f f} \\
{\left[\text { while }_{\text {ns }}^{\mathrm{tt}]}\right.} & \frac{\langle S, s\rangle \rightarrow s^{\prime},\left\langle\text { while } b \text { do } S, s^{\prime}\right\rangle \rightarrow s^{\prime \prime}}{\langle\text { while } b \text { do } S, s\rangle \rightarrow s^{\prime \prime}} \text { if } \mathcal{B} \llbracket b \rrbracket s=\mathbf{t t} \\
{[\text { while }} \\
& \langle\text { while } b \text { do } S, s\rangle \rightarrow s \text { if } \mathcal{B} \llbracket b \rrbracket s=\mathbf{f f}
\end{array}
$$

## Recall: Small-step operational semantics of While language

| $\left[\mathrm{ass}_{\mathrm{sos}}\right]$ | $\langle x:=a, s\rangle \Rightarrow s[x \mapsto \mathcal{A} \llbracket a \rrbracket s]$ |
| :--- | :--- |
| $\left[\mathrm{skip}_{\mathrm{sos}}\right]$ | $\langle\mathrm{skip}, s\rangle \Rightarrow s$ |
| $\left[\mathrm{comp}_{\mathrm{sos}}^{1}\right]$ | $\frac{\left\langle S_{1}, s\right\rangle \Rightarrow\left\langle S_{1}^{\prime}, s^{\prime}\right\rangle}{\left\langle S_{1} ; S_{2}, s\right\rangle \Rightarrow\left\langle S_{1}^{\prime} ; S_{2}, s^{\prime}\right\rangle}$ |
| $\left[\mathrm{comp}_{\mathrm{sos}}^{2}\right]$ | $\frac{\left\langle S_{1}, s\right\rangle \Rightarrow s^{\prime}}{\left\langle S_{1} ; S_{2}, s\right\rangle \Rightarrow\left\langle S_{2}, s^{\prime}\right\rangle}$ |
| $\left[\mathrm{if}_{\mathrm{sos}}^{\mathrm{tt}}\right]$ | $\left\langle\right.$ if $b$ then $S_{1}$ else $\left.S_{2}, s\right\rangle \Rightarrow\left\langle S_{1}, s\right\rangle$ if $\mathcal{B} \llbracket b \rrbracket s=$ tt |
| $\left[\mathrm{if}_{\mathrm{sos}}^{\mathrm{ff}}\right]$ | $\left\langle\right.$ if $b$ then $S_{1}$ else $\left.S_{2}, s\right\rangle \Rightarrow\left\langle S_{2}, s\right\rangle$ if $\mathcal{B} \llbracket b \rrbracket s=\mathbf{f f}$ |
| $\left[\right.$ while $\left._{\text {sos }}\right]$ | $\langle$ while $b$ do $S, s\rangle \Rightarrow$ |

## Denotational semantics of While language

$$
\begin{aligned}
& \mathcal{S}_{d s}: \text { Stm } \rightarrow(\text { State } \hookrightarrow \text { State }) \\
& \mathcal{S}_{d s}[x:=a] s=s[x \mapsto \mathcal{A}[a] s] \\
& \mathcal{S}_{d s}[\text { skip }]=\text { id } \\
& \mathcal{S}_{d s}\left[S_{1} ; S_{2}\right]=\mathcal{S}_{d s}\left[S_{2}\right] \circ \mathcal{S}_{d s}\left[S_{1}\right] \\
& \mathcal{S}_{d s}\left[\text { if } b \text { then } S_{1} \text { else } S_{2}\right]= \\
& \quad \operatorname{cond}\left(\mathcal{B}[b], \mathcal{S}_{d s}\left[S_{1}\right], \mathcal{S}_{d s}\left[S_{2}\right]\right)
\end{aligned}
$$

$$
F g=\operatorname{cond}\left(\mathcal{B}[b], g \circ \mathcal{S}_{d s}[S], \text { id }\right)
$$

More functional as opposed to operational style

## Auxiliary operators

$$
\begin{aligned}
& \text { id } s=s \\
& \qquad \begin{aligned}
&(f \circ g) s \\
&= \begin{cases}f(g s) & \text { if } g s \neq \text { undef } \\
\text { and } f(g s) \neq \text { undef } \\
\text { otherwise }\end{cases} \\
&= \begin{cases}g_{1} s & \text { if } p s=\mathrm{tt} \\
g_{2} s & \text { and } g_{1} s \neq \text { if } p=\mathrm{ff} \\
\text { and } g_{2} s \neq \text { undef } \\
\text { undef } & \text { otherwise }\end{cases} \\
&\left\{\begin{array}{l}
\text { undef }
\end{array}\right.
\end{aligned} .
\end{aligned}
$$

Partial function composition


This slide is derived from the book \& slides by Nelson \& Nelson: "Semantics with applications" (1991 \& 1999+).

## Interesting semantics of loops

$\mathcal{S}_{d s}[$ while $b$ do $S]=$ FIX $F$
where

$$
F g=\operatorname{cond}\left(\mathcal{B}[b], g \circ \mathcal{S}_{d s}[S], \mathrm{id}\right)
$$



$$
\begin{aligned}
& \mathcal{S}_{d s}[\text { while } b \text { do } S] \\
& =\mathcal{S}_{d s}[\text { if } b \text { then }(S \text {; while } b \text { do } S) \\
& \quad \text { else skip }] \\
& =\operatorname{cond}\left(\mathcal{B}[b], \mathcal{S}_{d s}[S ; \text { while } b \text { do } S],\right. \\
& \left.\quad \mathcal{S}_{d s}[\text { skip }]\right) \\
& =\operatorname{cond}\left(\mathcal{B}[b], \mathcal{S}_{d s}[\text { while } b \text { do } S] \circ \mathcal{S}_{d s}[S],\right. \\
& \quad \text { id }) \\
& =F\left(\mathcal{S}_{d s}[\text { while } b \text { do } S]\right)
\end{aligned}
$$

$\mathcal{S}_{d s}[$ while $b$ do $S]$ is a fixed point of $F$ !

## Fixed points

$$
\begin{aligned}
& \mathcal{S}_{d s}[\text { while } b \text { do } S]=\text { FIX } F \\
& \text { where } F g=\operatorname{cond}\left(\mathcal{B}[b], g \circ \mathcal{S}_{d s}[S] \text {, id }\right)
\end{aligned}
$$

- Type of FIX:

$$
\begin{gathered}
\text { FIX: }((\text { State } \hookrightarrow \text { State }) \rightarrow(\text { State } \hookrightarrow \text { State })) \\
\rightarrow(\text { State } \hookrightarrow \text { State })
\end{gathered}
$$

- Interesting questions:
- Will F always have a fixed point?
- If there are several, which one to choose?


## Definition of fixed point

Let $f: D \rightarrow D$ be a continuous function on the ccpo $(D, \sqsubseteq)$ with least element $\perp$. Then

$$
\text { FIX } f=\square\left\{f^{n} \perp \mid n \geq 0\right\}
$$

defines an element of $D$ and this element is the least fixed point of $f$.

> Remember fixed-point property: $$
\text { FIX } f=f(F I X f)
$$

## Chain-complete partially ordered sets (ccpo)

A subset $Y$ of $D$ is called a chain if for any two elements $d_{1}$ and $d_{2}$ in $Y$ either

$$
d_{1} \sqsubseteq d_{2} \text { or } d_{2} \sqsubseteq d_{1}
$$

( $D, \sqsubseteq$ ) is a chain complete partially ordered set (ccpo) if every chain of $D$ has a least upper bound.


## Partially ordered sets

A set $D$ with an ordering $\sqsubseteq$ that is


- reflexive

$$
d \sqsubseteq d
$$

- transitive

$$
d_{1} \sqsubseteq d_{2} \text { and } d_{2} \sqsubseteq d_{3} \text { imply } d_{1} \sqsubseteq d_{3}
$$

- anti-symmetric

$$
d_{1} \sqsubseteq d_{2} \text { and } d_{2} \sqsubseteq d_{1} \text { imply } d_{1}=d_{2}
$$

$d$ is a least element of $(D, \sqsubseteq)$ if $d \sqsubseteq d^{\prime}$ for all $d^{\prime}$.

If $(D, \sqsubseteq)$ has a least element then it is unique and is called $\perp$.

## Example for cpo (ccpo, complete lattice)



## Complete lattices



Let ( $D, \sqsubseteq$ ) be a partially ordered set and let $Y \subseteq D$.
$d$ is an upper bound on $Y$ if $d^{\prime} \sqsubseteq d$ for all $d^{\prime} \in Y$
$d$ is a least upper bound on $Y$ if

Complete lattices are ccpos.
$d$ is an upper bound on $Y$
if $d^{\prime}$ is an upper bound on $Y$ then $d \sqsubseteq d^{\prime}$.

## Continuos functions

Let ( $D, \sqsubseteq$ ) and ( $D^{\prime}, \sqsubseteq^{\prime}$ ) be ccpo's and consider a (total) function $f: D \rightarrow D^{\prime}$. Then $f$ is continuous if

- $f$ is monotone
- $\sqcup^{\prime}\{f d \mid d \in Y\}=f(\sqcup Y)$
for all non-empty chains $Y$ of $D$.


## Monotone functions

## Let ( $D, \sqsubseteq$ ) and ( $D^{\prime}, \sqsubseteq^{\prime}$ ) be ccpo's and consider a (total) function

$$
f: D \rightarrow D^{\prime}
$$

Then $f$ is monotone if
whenever $d_{1} \sqsubseteq d_{2}$ also $f d_{1} \sqsubseteq^{\prime} f d_{2}$

## Monotone functions



## Examples

$$
\begin{array}{c|c|c|}
f_{1}, f_{2}: \mathcal{P}(\{\mathrm{a}, \mathrm{~b}, \mathrm{c}\}) \rightarrow \mathcal{P}(\{\mathrm{d}, \mathrm{e}\}) \\
X & f_{1} X & f_{2} X \\
\hline\{\mathrm{a}, \mathrm{~b}, \mathrm{c}\} & \{\mathrm{d}, \mathrm{e}\} & \{\mathrm{d}\} \\
\{\mathrm{a}, \mathrm{~b}\} & \{\mathrm{d}\} & \{\mathrm{d}\} \\
\{\mathrm{a}, \mathrm{c}\} & \{\mathrm{d}, \mathrm{e}\} & \{\mathrm{d}\} \\
\{\mathrm{b}, \mathrm{c}\} & \{\mathrm{d}, \mathrm{e}\} & \{\mathrm{e}\} \\
\{\mathrm{a}\} & \{\mathrm{d}\} & \{\mathrm{d}\} \\
\{\mathrm{b}\} & \{\mathrm{d}\} & \{\mathrm{e}\} \\
\{\mathrm{c}\} & \{\mathrm{e}\} & \{\mathrm{e}\} \\
\emptyset & \emptyset & \{\mathrm{e}\} \\
\hline
\end{array}
$$

## Definition of fixed point

Let $f: D \rightarrow D$ be a continuous function on the ccpo ( $D, \sqsubseteq$ ) with least element $\perp$. Then

$$
\text { FIX } f=\sqcup\left\{f^{n} \perp \mid n \geq 0\right\}
$$

defines an element of $D$ and this element is the least fixed point of $f$.

Hence, if the semantic equations construct continuous functions, then the semantics of while loops is well-defined.

## What is the relationship between operational and denotational semantics?

$$
\left.\begin{array}{l}
(x:=a, s) \Rightarrow s[x \mapsto \mathcal{A}[a] s] \\
(\text { skip }, s) \Rightarrow s \\
\frac{\left(S_{1}, s\right) \Rightarrow\left(S_{1}^{\prime}, s^{\prime}\right)}{\left(S_{1} ; S_{2}, s\right) \Rightarrow\left(S_{1}^{\prime} ; S_{2}, s^{\prime}\right)} \\
\frac{\left(S_{1}, s\right) \Rightarrow s^{\prime}}{\left(S_{1} ; S_{2}, s\right) \Rightarrow\left(S_{2}, s^{\prime}\right)} \\
\left(\text { if } b \text { then } S_{1} \text { else } S_{2}, s\right) \Rightarrow\left(S_{1}, s\right) \\
\text { if } \mathcal{B}[b] s=\mathrm{tt}
\end{array}\right\} \begin{aligned}
& \text { (if } \left.b \text { then } S_{1} \text { else } S_{2}, s\right) \Rightarrow\left(S_{2}, s\right) \\
& \text { if } \mathcal{B}[b] s=\mathrm{ff} \\
& \text { (while } b \text { do } S, s) \Rightarrow \\
& \text { (if } b \text { then }(S ; \text { while } b \text { do } S) \text { else skip, } s)
\end{aligned}
$$



## Theorem about equivalence

For every statement $S$ of While we have


$$
\mathcal{S}_{s o s}[S]=\mathcal{S}_{d s}[S]
$$

where

$$
\mathcal{S}_{s o s}[S] s= \begin{cases}s^{\prime} & \text { if }(S, s) \Rightarrow^{*} s^{\prime} \\ \text { undefined } & \text { otherwise }\end{cases}
$$

## Extended While language (While with exceptions)



## Example

> begin while true do if $\mathrm{x}<0$ then raise exit
> $\quad$ else $\mathrm{x}:=\mathrm{x}-1$
> handle exit: $\mathrm{y}:=7$ end

How is the semantics modified?

## Continuations

- The continuation c of a program fragment $S$ is the effect of executing the remainder of the program.

$$
c \in \text { Cont }=\text { State } \hookrightarrow \text { State }
$$

- The continuation for the complete program is the identity function: the remainder of the program is "empty" so the state will not be changed.


## Calculating Continuations

Given

we want to obtain


Semantic function:

$$
\left.\mathcal{S}_{c s}: \text { Stm } \rightarrow \text { (Cont } \rightarrow \text { Cont }\right)
$$

## Continuation style

$$
\begin{aligned}
& \mathcal{S}_{c s}: \operatorname{Stm} \rightarrow(\text { Cont } \rightarrow \text { Cont }) \\
& \mathcal{S}_{c s}[x:=a] c s=c(s[x \mapsto \mathcal{A}[a] s]) \\
& \mathcal{S}_{c s}[\text { skip }]=\text { id } \\
& \mathcal{S}_{c s}\left[S_{1} ; S_{2}\right]=\mathcal{S}_{c s}\left[S_{1}\right] \circ \mathcal{S}_{c s}\left[S_{2}\right] \\
& \mathcal{S}_{c s}\left[\text { if } b \text { then } S_{1} \text { else } S_{2}\right] c= \\
& \quad \text { cond }\left(\mathcal{B}[b], \mathcal{S}_{c s}\left[S_{1}\right] c, \mathcal{S}_{c s}\left[S_{2}\right] c\right) \\
& \mathcal{S}_{c s}[\text { while } b \text { do } S]=\text { FIX } G \\
& \quad \text { where } \\
& \quad(G g) c=\operatorname{cond}\left(\mathcal{B}[b], \mathcal{S}_{c s}[S](g c), c\right)
\end{aligned}
$$

## Direct style again (for comparison)

$$
\begin{aligned}
& \mathcal{S}_{d s}: \text { Stm } \rightarrow(\text { State } \hookrightarrow \text { State }) \\
& \mathcal{S}_{d s}[x:=a] s=s[x \mapsto \mathcal{A}[a] s] \\
& \mathcal{S}_{d s}[\text { skip }]=\text { id } \\
& \mathcal{S}_{d s}\left[S_{1} ; S_{2}\right]=\mathcal{S}_{d s}\left[S_{2}\right] \circ \mathcal{S}_{d s}\left[S_{1}\right] \\
& \mathcal{S}_{d s}\left[\text { if } b \text { then } S_{1} \text { else } S_{2}\right]= \\
& \quad \operatorname{cond}\left(\mathcal{B}[b], \mathcal{S}_{d s}\left[S_{1}\right], \mathcal{S}_{d s}\left[S_{2}\right]\right) \\
& \mathcal{S}_{d s}[\text { while } b \text { do } S]=\mathrm{FIX} F \\
& \text { where } \\
& \quad F g=\operatorname{cond}\left(\mathcal{B}[b], g \circ \mathcal{S}_{d s}[S], \text { id }\right)
\end{aligned}
$$

## Meaning of";'"

$$
\begin{aligned}
& \mathcal{S}_{d s}\left[S_{1} ; S_{2}\right]=\mathcal{S}_{d s}\left[S_{2}\right] \circ \mathcal{S}_{d s}\left[S_{1}\right] \\
& \mathcal{S}_{c s}\left[S_{1} ; S_{2}\right]=\mathcal{S}_{c s}\left[S_{1}\right] \circ \mathcal{S}_{c s}\left[S_{2}\right]
\end{aligned}
$$

In direct style, the state transformer of $S_{\text {I }}$ must be applied first and the one of $S_{2}$ second. In continuation style, the meaning of the second statement is the continuation of the first, and hence order is inverted.

## Consolidation

How do the two semantics relate to each other? For all statements $S$ of While and all continuations c of Cont:

$$
\mathcal{S}_{c s}[S] c=c \circ \mathcal{S}_{d s}[S]
$$

## Exceptions

```
S ::= ..
        begin }\mp@subsup{S}{1}{}\mathrm{ handle e: S}\mp@subsup{S}{2}{}\mathrm{ end
        raise e
```

- Exception environments
- map exception names to their meanings.
- the handle statement updates the environment.
- the raise statement inspects the environment.
- Semantic function for statements:

$$
\mathcal{S}_{c s}: \text { Stm } \rightarrow \text { EEnv } \rightarrow \text { Cont } \rightarrow \text { Cont }
$$

## Meaning of exceptions

What is the meaning of an exception:
the effect of executing the rest of the program from the definition point of the exception
i.e.: a continuation!

## Exception environment

$$
\text { EEnv }=\text { Ename } \rightarrow \text { Cont }
$$

$$
\begin{align*}
& \mathcal{S}_{c s}[x:=a] \text { eenv c } s=c(s[x \mapsto \mathcal{A}[a] s]) \\
& \mathcal{S}_{c s} \text { [skip] eenv }=\mathrm{id} \\
& \mathcal{S}_{c s}\left[S_{1} ; S_{2}\right] e e n v= \\
& \left(\mathcal{S}_{c s}\left[S_{1}\right] e e n v\right) \circ\left(\mathcal{S}_{c s}\left[S_{2}\right] e e n v\right) \\
& \mathcal{S}_{c s}\left[\text { if } b \text { then } S_{1} \text { else } S_{2}\right] \text { eenv } c= \\
& \operatorname{cond}\left(\mathcal{B}[b], \mathcal{S}_{c s}\left[S_{1}\right] \text { eenv } c\right. \text {, } \\
& \left.\mathcal{S}_{c s}\left[S_{2}\right] \text { eenv } c\right) \\
& \mathcal{S}_{c s}[\text { while } b \text { do } S] \text { een } v=\operatorname{FIX} G \\
& \text { where } \\
& (G g) c=\operatorname{cond}\left(\mathcal{B}[b], \mathcal{S}_{c s}[S] \text { eenv }(g c)\right. \text {, } \\
& \mathcal{S}_{c s}\left[\text { begin } S_{1} \text { handle } e: S_{2} \text { end }\right] \text { eenv } c= \\
& \mathcal{S}_{c s}\left[S_{1}\right]\left(e e n v\left[e \mapsto\left(\mathcal{S}_{c s}\left[S_{2}\right] \text { eenv } c\right)\right]\right) c \\
& \mathcal{S}_{c s}[\text { raise } e] \text { eenv } c=e e n v e
\end{align*}
$$

This slide is derived from the book \& slides by Nielson \& Nielson: "Semantics with applications" (1991 \& 1999+).

## Extended While language (While with declarations)

$$
\begin{aligned}
& S \quad::=x:=a \mid \text { skip } \mid S_{1} ; S_{2} \\
& \text { if } b \text { then } S_{1} \text { else } S_{2} \\
& \text { while } b \text { do } S \\
& \text { begin } D_{V} D_{P} S \text { end } \\
& \text { call } p \\
& D_{V}::=\operatorname{var} x:=a ; D_{V} \mid \epsilon \\
& D_{P}::=\operatorname{proc} p \text { is } S ; D_{P} \mid \epsilon
\end{aligned}
$$



How is the semantics modified?

- static scope?
- dynamic scope?


## A revised semantic function



## Refinement of states to deal with scopes

$\left.\begin{array}{|lll} & \text { variables } \longrightarrow \text { locations } & \longrightarrow\end{array}\right)$ values

Technically:

$$
s \in \text { State }=\operatorname{Var} \rightarrow \mathrm{Z}
$$

is replaced by

$$
\begin{aligned}
& \text { env } \in \mathrm{Env}=\mathrm{Var} \rightarrow \text { Loc and } \\
& \text { sto } \in \text { Store }=\mathrm{Loc} \rightarrow \mathrm{Z}
\end{aligned}
$$

## Denotational semantics

## with locations

$$
\begin{gathered}
\mathcal{S}_{d s}^{\prime}[x:=a] e n v \text { sto }= \\
\text { sto }[l \mapsto \mathcal{A}[a](\text { lookup env sto })]) \\
\text { where } l=\text { env } x \\
\mathcal{S}_{d s}^{\prime}[\text { skip }] \text { env }=\text { id } \\
\mathcal{S}_{d s}^{\prime}\left[S_{1} ; S_{2}\right] e n v= \\
\left(\mathcal{S}_{d s}^{\prime}\left[S_{2}\right] \text { env }\right) \circ\left(\mathcal{S}_{d s}^{\prime}\left[S_{1}\right] \text { env }\right) \\
\mathcal{S}_{d s}^{\prime}\left[\text { if } b \text { then } S_{1} \text { else } S_{2}\right] \text { env }= \\
\operatorname{cond}(\mathcal{B}[b] \circ(\text { lookup env }) \\
\mathcal{S}_{d s}^{\prime}\left[S_{1}\right] \text { env, } \\
\left.\mathcal{S}_{d s}^{\prime}\left[S_{2}\right] e n v\right)
\end{gathered}
$$

$$
\begin{aligned}
& \mathcal{S}_{d s}^{\prime}[\text { while } b \text { do } S] \text { env }=\text { FIX } F \\
& \text { where } \\
& F g=\operatorname{cond}(\mathcal{B}[b] \circ(\text { lookup env }), \\
& g \circ\left(\mathcal{S}_{d s}^{\prime}[S] \text { env }\right),
\end{aligned}
$$

id)

## Variable declarations

$D_{V}::=\operatorname{var} x:=a ; D_{V} \mid \epsilon$

- updates the environment:
$x$ is given a new location $l$
- updates the store:
$l$ is given the value of $a$
Two ways to get new locations

1. from the environment:

- Env $=($ Var $\rightarrow$ Loc $) \times$ Loc
$-\operatorname{Env}=($ Var $\cup\{n e x t\}) \rightarrow$ Loc

2. from the store:

- Store $=($ Loc $\rightarrow Z) \times$ Loc
- Store $=($ Loc $\cup\{n e x t\}) \rightarrow$

But the semantics are different!

## Variable declarations

$$
\begin{gathered}
\mathcal{D}_{V}: \operatorname{Dec}_{V} \rightarrow \text { Env } \times \text { Store } \rightarrow \text { Env } \times \text { Store } \\
\mathcal{D}_{V}\left[\operatorname{var} x:=a ; D_{V}\right](\text { env, sto })= \\
\mathcal{D}_{V}\left[D_{V}\right](e n v[x \mapsto l], \\
\text { sto }[l \mapsto v][\text { next } \mapsto \text { new sto }]) \\
\text { where } l=\text { sto (next) } \\
\text { and } v=\mathcal{A}[a] \text { (lookup env sto) } \\
\mathcal{D}_{V}[\epsilon]=\text { id } \\
\mathcal{S}_{d s}^{\prime}: \operatorname{Stm} \rightarrow \text { Env } \rightarrow \text { Store } \hookrightarrow \text { Store } \\
\mathcal{S}_{d s}^{\prime}\left[\text { begin } D_{V} S \text { end }\right] \text { env sto }= \\
\mathcal{S}_{d s}^{\prime}[S] e n v^{\prime} \text { sto }
\end{gathered}
$$

## Procedure declarations

$$
\begin{aligned}
& D_{P}::=\operatorname{proc} p \text { is } S ; D_{P} \mid \epsilon \\
& S::=\cdots \mid \text { call } p
\end{aligned}
$$

Procedure environments:

- map procedure names to their meanings
- are updated by procedure declarations
- are inspected by procedure calls

Semantic function for statements:

$$
\begin{aligned}
\mathcal{S}_{d s}^{\prime}: \text { Stm } & \rightarrow \text { Env } \rightarrow \text { PEnv } \\
& \rightarrow \text { Store } \hookrightarrow \text { Store }
\end{aligned}
$$

## The meaning of procedures

Four choices for meanings of procedures:

- Env $\rightarrow$ PEnv $\rightarrow$ Store $\hookrightarrow$ Store
- PEnv $\rightarrow$ Store $\hookrightarrow$ Store
- Env $\rightarrow$ Store $\hookrightarrow$ Store
- Store $\hookrightarrow$ Store


But the semantics are different!

$$
\text { PEnv }=\text { Pname } \rightarrow \text { (Store } \hookrightarrow \text { Store })
$$

## Procedure declarations

$$
\begin{aligned}
& \mathcal{D}_{P}: \operatorname{Dec}_{P} \rightarrow \text { Env } \rightarrow \text { PEnv } \rightarrow \text { PEnv } \\
& \mathcal{D}_{P}\left[\operatorname{proc} p \text { is } S ; D_{P}\right] \text { env penv }= \\
& \quad \mathcal{D}_{P}\left[D_{P}\right] \text { env penv }[p \mapsto F I X F] \\
& \text { where } F g=\mathcal{S}_{d s}^{\prime}[S] \text { env penv }[p \mapsto g] \\
& \mathcal{D}_{P}[\epsilon] \text { env }=\text { id } \\
& \mathcal{S}_{d s}^{\prime}: \text { Stm } \rightarrow \text { Env } \rightarrow \text { PEnv } \rightarrow \text { Store } \hookrightarrow \text { Store } \\
& \mathcal{S}_{d s}^{\prime}\left[\text { begin } D_{V} D_{P} S \text { end }\right] \text { env penv sto }= \\
& \quad \mathcal{S}_{d s}^{\prime}[S] e n v^{\prime} \text { penv } v^{\prime} \text { sto' } \\
& \text { where }\left(e n v^{\prime}, \text { sto }\right)=\mathcal{D}_{V}\left[D_{V}\right](e n v, \text { sto }) \\
& \text { and penv } \left.=\mathcal{D}_{P}\left[D_{P}\right] e n v^{\prime} \text { penv }\right) \\
& \mathcal{S}_{d s}^{\prime}[\text { call } p] \text { env penv }=\text { penv } p
\end{aligned}
$$

## Scope rules

- Dynamic scope for variables and procedures
- Dynamic scope for variables but static for procedures
- Static scope for variables as well as procedures

```
begin var* xy:= 0;
    proc'p,is x := x * 2;
    proc q}\mathrm{ is call p;
    begin var' }x=:=5
        procep,is x := x + 1;
        call "q;; y := x
    end
end
```


## Option: dynamic scope for variables and procedures

```
begin var x := 0;
    proc p is x := x * 2;
    proc q is call p;
    begin var x := 5;
        proc p is x := x + 1;
        call q; y := x
    end
end
```

- Execution
+ call q
+ call p (calls inner, say local p)

+ $x:=x+1$ (affects inner, say local $\times$ )
+ $y$ := x (obviously accesses local $\times$ )
- Final value of $y=6$

Option: dynamic scope for variables static scope for procedures

- Execution
+ call q
+ call p (calls outer, say global p)

$+x:=x^{*} 2$ (affects inner, say local $x$ )
$+y$ := $\times$ (obviously accesses local $x$ )
- Final value of $y=10$

Option: static scope for variables and procedures

- Execution
+ call q
+ call p (calls outer, say global p)

+ $x$ := x*2 (affects outer, say global $x$ )
$+y$ := x (obviously accesses local $x$ )
- Final value of $y=5$
- Summary: Denotational semantics
+ Direct style: meanings are state transformers.
+ Continuation style: meanings take "rest of program".
+ States can be split into environments \& locations.
+ Denotational semantics are easily written in Haskell.
- Prepping: "Semantics with applications"
+ Chapter on denotational semantics
- Outlook:
+ Program analysis

